# <span id="page-0-0"></span>Lecture 18: Finding Inverse Matrices by Gauss-Jordan Elimination

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MATH3200: Applied Linear Algebra

## Review: The definition of the matrix inverse

Let **A** be an  $n \times n$  square matrix.

The *inverse of* **A** is an  $n \times n$  matrix  $\mathbf{A}^{-1}$  such that

 $A^{-1}A = I_{n}$ 

#### Theorem

The inverse  $A^{-1}$ , if it exists, is unique and satisfies  $AA^{-1} = I_n$ .

When **A** is a zero matrix, then **A** does not have an inverse.

For  $n > 1$ , there are infinitely many more examples of non-invertible aka singular matrices **A** of order  $n \times n$ , that is matrices that do not have an inverse matrix  $\mathsf{A}^{-1}.$ 

If  $A^{-1}$  exists, then A is *invertible* or *non-singular*.

## How to find inverse matrices?

We have seen that:

- It is easy to verify that a given pair of matrices are inverses of each other (multiply them and check whether the product is an identity matrix I).
- It can be *relatively easy* to find  $A^{-1}$  when A is a diagonal matrix.
- But how do we find  $A^{-1}$  in general? Even for a seemingly simple matrix like

$$
\mathbf{A} = \begin{bmatrix} 0.5 & 0.5 & 0 \\ 0.5 & 0 & 0.5 \\ 0 & 0.5 & 0.5 \end{bmatrix}
$$

this seems hard.

#### An observation

An  $n \times n$  matrix **A** can have an inverse only if Gaussian elimination produces a matrix with all diagonal elements equal to 1. For  $n = 3$  this looks as follows:

$$
\begin{bmatrix} a_{11} & a_{12} & a_{13} \ a_{21} & a_{22} & a_{23} \ a_{31} & a_{32} & a_{33} \end{bmatrix}
$$
 Gaussian elimination 
$$
\begin{bmatrix} 1 & ? & ? \ 0 & 1 & ? \ 0 & 0 & 1 \end{bmatrix}
$$

Now we can keep going and apply elementary row operation (E3) more times until we get I:

$$
\begin{bmatrix} 1 & ? & ? \\ 0 & 1 & ? \\ 0 & 0 & 1 \end{bmatrix}
$$
 More applications of (E3) 
$$
\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}
$$

So what? How could this help?

## A magic trick: Gauss-Jordan elimination

Let **A** be an  $n \times n$  matrix. Form an  $n \times 2n$  matrix **C** by dropping the internal brackets in  $[A, I_n]$  and replacing them with a vertical dividing line for visual clarity. For  $n = 3$  we get:



Perform Gaussian elimination. If the first half of the resulting matrix in row-echelon form has a zero row, then  $A$  is not invertible. *Otherwise* keep going and apply instances of  $(E3)$  until the first half turns into  $I_n$  so that the entire matrix is in reduced row echelon form. For  $n = 3$  the result will look like:

$$
\begin{bmatrix} 1 & 0 & 0 & b_{11} & b_{12} & b_{13} \\ 0 & 1 & 0 & b_{21} & b_{22} & b_{23} \\ 0 & 0 & 1 & b_{31} & b_{32} & b_{33} \end{bmatrix}
$$

Let's see what we get for the matrix B in the second half.

### Trying out the magic trick

Let 
$$
\mathbf{A} = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}
$$
 Here we already know  $\mathbf{A}^{-1} = \begin{bmatrix} -2 & 1 \\ 1.5 & -0.5 \end{bmatrix}$ 

Form a 2  $\times$  4 matrix **C** and perform Gaussian elimination on it:

$$
\mathbf{C} = \begin{bmatrix} 1 & 2 & 1 & 0 \\ 3 & 4 & 0 & 1 \end{bmatrix} \xrightarrow{R2 \rightarrow R2-3R1} \begin{bmatrix} 1 & 2 & 1 & 0 \\ 0 & -2 & -3 & 1 \end{bmatrix}
$$

$$
\begin{bmatrix} 1 & 2 & 1 & 0 \\ 0 & -2 & -3 & 1 \end{bmatrix} \xrightarrow{R2 \rightarrow R2/(-2)} \begin{bmatrix} 1 & 2 & 1 & 0 \\ 0 & 1 & 1.5 & -0.5 \end{bmatrix}
$$

Apply (E3) one more time to turn the first half into  $I_2$ :

$$
\begin{bmatrix} 1 & 2 & 1 & 0 \ 0 & 1 & 1.5 & -0.5 \end{bmatrix} \xrightarrow{R1 \rightarrow R1-2R2} \begin{bmatrix} 1 & 0 & -2 & 1 \ 0 & 1 & 1.5 & -0.5 \end{bmatrix}
$$

Magically, the matrix B in the right half is  $A^{-1}$ !

#### Trying the magic trick on another matrix

Let 
$$
\mathbf{A} = \begin{bmatrix} 0.5 & 0.5 & 0 \\ 0.5 & 0 & 0.5 \\ 0 & 0.5 & 0.5 \end{bmatrix}
$$
 Here we don't know  $\mathbf{A}^{-1}$ .

Form a  $3 \times 6$  matrix **C** and perform Gaussian elimination on it. Start by subtracting row 1 from row 2:

$$
\mathbf{C} = \begin{bmatrix} 0.5 & 0.5 & 0 & 1 & 0 & 0 \\ 0.5 & 0 & 0.5 & 0 & 1 & 0 \\ 0 & 0.5 & 0.5 & 0 & 0 & 1 \end{bmatrix} \longrightarrow \begin{bmatrix} 0.5 & 0.5 & 0 & 1 & 0 & 0 \\ 0 & -0.5 & 0.5 & -1 & 1 & 0 \\ 0 & 0.5 & 0.5 & 0 & 0 & 1 \end{bmatrix}
$$

Next add row 2 to row 3:

$$
\begin{bmatrix} 0.5 & 0.5 & 0 & 1 & 0 & 0 \\ 0 & -0.5 & 0.5 & -1 & 1 & 0 \\ 0 & 0.5 & 0.5 & 0 & 0 & 1 \end{bmatrix} \longrightarrow \begin{bmatrix} 0.5 & 0.5 & 0 & 1 & 0 & 0 \\ 0 & -0.5 & 0.5 & -1 & 1 & 0 \\ 0 & 0 & 1 & -1 & 1 & 1 \end{bmatrix}
$$

## Trying the magic trick on another matrix, continued

Multiply row 1 by 2:

$$
\begin{bmatrix} 0.5 & 0.5 & 0 & 1 & 0 & 0 \ 0 & -0.5 & 0.5 & -1 & 1 & 0 \ 0 & 0 & 1 & -1 & 1 & 1 \end{bmatrix} \longrightarrow \begin{bmatrix} 1 & 1 & 0 & 2 & 0 & 0 \ 0 & -0.5 & 0.5 & -1 & 1 & 0 \ 0 & 0 & 1 & -1 & 1 & 1 \end{bmatrix}
$$

Multiply row 2 by -2:

$$
\begin{bmatrix} 1 & 1 & 0 & 2 & 0 & 0 \ 0 & -0.5 & 0.5 & -1 & 1 & 0 \ 0 & 0 & 1 & -1 & 1 & 1 \end{bmatrix} \longrightarrow \begin{bmatrix} 1 & 1 & 0 & 2 & 0 & 0 \ 0 & 1 & -1 & 2 & -2 & 0 \ 0 & 0 & 1 & -1 & 1 & 1 \end{bmatrix}
$$

The first half is now in row echelon form.

#### Question L18.1: Are we done?

Not yet. We still need to get rid of the nonzero off-diagonal elements in the first half of this matrix.

Add row 3 to row 2:

$$
\begin{bmatrix} 1 & 1 & 0 & 2 & 0 & 0 \ 0 & 1 & -1 & 2 & -2 & 0 \ 0 & 0 & 1 & -1 & 1 & 1 \end{bmatrix} \longrightarrow \begin{bmatrix} 1 & 1 & 0 & 2 & 0 & 0 \ 0 & 1 & 0 & 1 & -1 & 1 \ 0 & 0 & 1 & -1 & 1 & 1 \end{bmatrix}
$$

Question L18.2: What should we do next?

Subtract row 2 from row 1:

$$
\begin{bmatrix} 1 & 1 & 0 & 2 & 0 & 0 \ 0 & 1 & 0 & 1 & -1 & 1 \ 0 & 0 & 1 & -1 & 1 & 1 \end{bmatrix} \longrightarrow \begin{bmatrix} 1 & 0 & 0 & 1 & 1 & -1 \ 0 & 1 & 0 & 1 & -1 & 1 \ 0 & 0 & 1 & -1 & 1 & 1 \end{bmatrix}
$$

Did the magic work? We will verify this by hand.

This magic trick is often called Gauss-Jordan elimination.

To see why it works, it will be most convenient to treat the matrix  $[A, I_n]$  and the matrix C that is obtained from it after dropping the internal brackets as the same object (shown for  $n = 3$ ):

$$
\mathbf{C} = \begin{bmatrix} a_{11} & a_{12} & a_{13} \ a_{21} & a_{22} & a_{23} \ a_{31} & a_{32} & a_{33} \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \ 0 & 1 & 0 \ 0 & 0 & 1 \end{bmatrix} = [\mathbf{A}, \mathbf{I}_n]
$$

The end result of the procedure can be written as follows (first the special case for  $n = 3$ , then the general case is shown):

$$
\begin{bmatrix} 1 & 0 & 0 & b_{11} & b_{12} & b_{13} \ 0 & 1 & 0 & b_{21} & b_{22} & b_{23} \ 0 & 0 & 1 & b_{31} & b_{32} & b_{33} \end{bmatrix} = [\mathbf{I}_n, \mathbf{B}]
$$

 $C = [A, I_n]$ 

**Question L18.3:** What does multiplying C from the left with  $E_1$ do to the matrices **A** and  $I_n$ ?

#### $E_1C = E_1[A, I_n]$

These operations do *the same thing* to the two matrices in the expression on the right:

 $[E_1A, E_1I_n]$ 

#### $E_2E_1C = E_2E_1[A, I_n]$

These operations do *the same thing* to the two matrices in the expression on the right:

 $[E_2E_1A, E_2E_1I_n]$ 

#### $E_3E_2E_1C = E_3E_2E_1[A, I_n]$

These operations do *the same thing* to the two matrices in the expression on the right:

 $[E_3E_2E_1A, E_3E_2E_1I_n]$ 

#### ...  $E_3E_2E_1C = ... E_3E_2E_1[A, I_n]$

These operations do *the same thing* to the two matrices in the expression on the right:

[... $E_3E_2E_1A$ , ... $E_3E_2E_1I_n$ ]

## Why does the magic trick work?

The procedure involves successively applying elementary row operations to the matrix  $C$ . These can be implemented by successively multiplying  $C$  from the left by elementary matrices  $E_1, E_2, E_3, \ldots, E_k$ :

$$
\textbf{E}_k \ldots \textbf{E}_3 \textbf{E}_2 \textbf{E}_1 \textbf{C} = \textbf{E}_k \ldots \textbf{E}_3 \textbf{E}_2 \textbf{E}_1 [\textbf{A}, \textbf{I}_n]
$$

These operations do *the same thing* to the two matrices in the expression on the right:

 $[E_k ... E_3E_2E_1A, E_k ... E_3E_2E_1I_n] = [I_n, B]$ 

The second coordinate shows that

 $B = E_k ... E_3E_2E_1I_n = E_k ... E_3E_2E_1$ .

The first coordinate shows that  $(E_k \dots E_3E_2E_1)A = BA = I_n$ . It follows that  $B = A^{-1}$ .

## Practice: One more example of Gauss-Jordan elimination

Let 
$$
\mathbf{A} = \begin{bmatrix} 0 & 0.5 \\ 1 & 2 \end{bmatrix}
$$
 We want to find  $\mathbf{A}^{-1}$ .

Form a 2 × 4 matrix 
$$
\mathbf{C} = \begin{bmatrix} 0 & 0.5 & 1 & 0 \\ 1 & 2 & 0 & 1 \end{bmatrix}
$$
.

Question L18.4: What should we do next?

Switch rows 1 and 2:

$$
\begin{bmatrix} 0 & 0.5 & 1 & 0 \\ 1 & 2 & 0 & 1 \end{bmatrix} \overset{\mathcal{R}1\leftrightarrow\mathcal{R}2}{\longrightarrow} \begin{bmatrix} 1 & 2 & 0 & 1 \\ 0 & 0.5 & 1 & 0 \end{bmatrix}
$$

Question L18.5: What should we do next?

Multiply row 2 by 2:

$$
\begin{bmatrix} 1 & 2 & 0 & 1 \\ 0 & 0.5 & 1 & 0 \end{bmatrix} \overset{R2 \mapsto 2R2}{\longrightarrow} \begin{bmatrix} 1 & 2 & 0 & 1 \\ 0 & 1 & 2 & 0 \end{bmatrix}
$$

Practice example of Gauss-Jordan elimination, completed

Let 
$$
\mathbf{A} = \begin{bmatrix} 0 & 0.5 \\ 1 & 2 \end{bmatrix}
$$
 We want to find  $\mathbf{A}^{-1}$ .

We formed a 2 × 4 matrix 
$$
\mathbf{C} = \begin{bmatrix} 0 & 0.5 & 1 & 0 \\ 1 & 2 & 0 & 1 \end{bmatrix}
$$
  
and transformed it into  $\begin{bmatrix} 1 & 2 & 0 & 1 \\ 0 & 1 & 2 & 0 \end{bmatrix}$ 

Question L18.6: What should we do next?

Subtract 2 times row 2 from row 1:

$$
\begin{bmatrix} 1 & 2 & 0 & 1 \ 0 & 1 & 2 & 0 \end{bmatrix} \xrightarrow{R2 \to R1-2R2} \begin{bmatrix} 1 & 0 & -4 & 1 \ 0 & 1 & 2 & 0 \end{bmatrix}
$$
  
The matrix  $\mathbf{B} = \begin{bmatrix} -4 & 1 \ 2 & 0 \end{bmatrix}$  in the right half is  $\mathbf{A}^{-1}$ 

## <span id="page-18-0"></span>Summary: A magic trick aka Gauss-Jordan elimination

Let **A** be an  $n \times n$  matrix. Form an  $n \times 2n$  matrix **C** by dropping the internal brackets in  $[A, I_n]$  and replacing them with a vertical dividing line for visual clarity. For  $n = 3$  we get:



Perform Gaussian elimination. If the first half of the resulting matrix in row-echelon form has a zero row, then  $A$  is not invertible. *Otherwise* keep going and apply instances of (E3) until the first half turns into  $I_n$  so that the entire matrix is in reduced row echelon form. For  $n = 3$  the result will look like:

$$
\begin{bmatrix} 1 & 0 & 0 & b_{11} & b_{12} & b_{13} \ 0 & 1 & 0 & b_{21} & b_{22} & b_{23} \ 0 & 0 & 1 & b_{31} & b_{32} & b_{33} \end{bmatrix}
$$

The matrix B in the second half will be the inverse  $A^{-1}$ .

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