

**MATH3200: APPLIED LINEAR ALGEBRA**  
**SELF-STUDY AND PRACTICE MODULE 55B: MATRIX**  
**REPRESENTATION OF LINEAR TRANSFORMATIONS**

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This module is based on Lecture 30 and Conversation 30A. Recall the following theorem from this Conversation:

**Theorem 1** (Matrix representation of linear transformations). *Suppose  $L : \mathbb{R}^n \rightarrow \mathbb{R}^m$  is a linear transformation. If both the elements of the domain  $\mathbb{R}^n$  of  $L$  and the function values  $L(\vec{x})$  in  $\mathbb{R}^m$  are treated as column vectors. Then there exists a matrix  $\mathbf{A}$  of order  $m \times n$  such that  $L = L_{\mathbf{A}}$ , that is,  $L(\vec{x}) = \mathbf{A}\vec{x}$  for all  $\vec{x}$  in  $\mathbb{R}^n$ .*

**Proof of Theorem 1:** Let us analyze a proof of this theorem here.

Recall that if we treat  $\mathbb{R}^n$  as a space of column vectors, then the standard basis vectors are

$$\vec{e}_1 = \begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix} \quad \vec{e}_2 = \begin{bmatrix} 0 \\ 1 \\ \vdots \\ 0 \end{bmatrix} \quad \dots \quad \vec{e}_n = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 1 \end{bmatrix}$$

Thus every vector  $\vec{x} \in \mathbb{R}^n$  can be uniquely expressed as a linear combination

$$\vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = x_1 \begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix} + x_2 \begin{bmatrix} 0 \\ 1 \\ \vdots \\ 0 \end{bmatrix} + \dots + x_n \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 1 \end{bmatrix} = x_1 \vec{e}_1 + x_2 \vec{e}_2 + \dots + x_n \vec{e}_n.$$

Now let  $L : \mathbb{R}^n \rightarrow \mathbb{R}^m$  be a linear transformation. Consider the  $m \times 1$  column vectors

$$L(\vec{e}_1) = \begin{bmatrix} a_{11} \\ a_{21} \\ \vdots \\ a_{m1} \end{bmatrix} \quad L(\vec{e}_2) = \begin{bmatrix} a_{12} \\ a_{22} \\ \vdots \\ a_{m2} \end{bmatrix} \quad \dots \quad L(\vec{e}_n) = \begin{bmatrix} a_{1n} \\ a_{2n} \\ \vdots \\ a_{mn} \end{bmatrix}$$

Let us form an  $m \times n$  matrix  $\mathbf{A}$  with these columns:

$$\mathbf{A} = [L(\vec{e}_1), L(\vec{e}_2), \dots, L(\vec{e}_n)] = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix}$$

We want to show that  $L$  is the same linear transformation as the linear transformation  $L_{\mathbf{A}}$  that is defined by  $L_{\mathbf{A}}(\vec{x}) = \mathbf{A}\vec{x}$  for every vector  $\vec{x} \in \mathbb{R}^n$ .

Let us first calculate the values  $L_{\mathbf{A}}(\vec{e}_j)$  for the standard basis vectors  $\vec{e}_j$ .

$$(1) \quad L_{\mathbf{A}}(\vec{\mathbf{e}}_1) = \mathbf{A}\vec{\mathbf{e}}_1 = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix} = \begin{bmatrix} a_{11} \\ a_{21} \\ \vdots \\ a_{m1} \end{bmatrix} = L(\vec{\mathbf{e}}_1)$$

**Question 55.10:** Where does the last equality in (1) come from?

Similarly,

$$L_{\mathbf{A}}(\vec{\mathbf{e}}_2) = \mathbf{A}\vec{\mathbf{e}}_2 = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix} \begin{bmatrix} 0 \\ 1 \\ \vdots \\ 0 \end{bmatrix} = \begin{bmatrix} a_{12} \\ a_{22} \\ \vdots \\ a_{m2} \end{bmatrix} = L(\vec{\mathbf{e}}_2)$$

(and so on ...)

$$L_{\mathbf{A}}(\vec{\mathbf{e}}_n) = \mathbf{A}\vec{\mathbf{e}}_n = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 1 \end{bmatrix} = \begin{bmatrix} a_{1n} \\ a_{2n} \\ \vdots \\ a_{mn} \end{bmatrix} = L(\vec{\mathbf{e}}_n)$$

We have shown that for  $j = 1, 2, \dots, n$ :

$$L_{\mathbf{A}}(\vec{\mathbf{e}}_j) = \mathbf{A}\vec{\mathbf{e}}_j = L(\vec{\mathbf{e}}_j).$$

Now let  $\vec{\mathbf{x}}$  be any vector in  $\mathbb{R}^n$ . Then

$$\vec{\mathbf{x}} = x_1\vec{\mathbf{e}}_1 + x_2\vec{\mathbf{e}}_2 + \cdots + x_n\vec{\mathbf{e}}_n,$$

and it follows from the linearity of  $L_{\mathbf{A}}$  that

$$L_{\mathbf{A}}(\vec{\mathbf{x}}) = x_1L_{\mathbf{A}}(\vec{\mathbf{e}}_1) + x_2L_{\mathbf{A}}(\vec{\mathbf{e}}_2) + \cdots + x_nL_{\mathbf{A}}(\vec{\mathbf{e}}_n).$$

From what we have already shown it follows that

$$(2) \quad L_{\mathbf{A}}(\vec{\mathbf{x}}) = x_1L(\vec{\mathbf{e}}_1) + x_2L(\vec{\mathbf{e}}_2) + \cdots + x_nL(\vec{\mathbf{e}}_n) = L(\vec{\mathbf{x}}).$$

**Question 55.11:** Where does the last equality in (2) come from?

Thus the two functions  $L_{\mathbf{A}}$  and  $L$  take the same values for all inputs  $\vec{\mathbf{x}}$  and must be the same function.  $\square$