MATH3200: APPLIED LINEAR ALGEBRA PRACTICE MODULE 64: DETERMINANTS AND PROPERTIES OF LINEAR TRANSFORMATIONS

WINFRIED JUST, OHIO UNIVERSITY

This module is based on Lecture 34. Recall the following theorems from this lecture:

Theorem 1. Let **A** be a matrix of order 2×2 and let $L_{\mathbf{A}} : \mathbb{R}^2 \to \mathbb{R}^2$ be the transformation of the Euclidean plane that is defined by **A**. Then

- (i) $L_{\mathbf{A}}$ maps any region of area A onto a region of area $|\det(\mathbf{A})|A$.
- (ii) If $det(\mathbf{A}) > 0$, then $L_{\mathbf{A}}$ preserves orientation.
- (iii) If $det(\mathbf{A}) < 0$, then $L_{\mathbf{A}}$ reverses orientation.
- (iv) If $det(\mathbf{A}) = 0$, then $L_{\mathbf{A}}$ maps \mathbb{R}^2 to a lower-dimensional subspace.

Theorem 2. Let **A** be a matrix of order 3×3 and let $L_{\mathbf{A}} : \mathbb{R}^3 \to \mathbb{R}^3$ be the transformation of the Euclidean space that is defined by **A**. Then

- (i) $L_{\mathbf{A}}$ maps any region of volume V onto a region of volume $|\det(\mathbf{A})|V$.
- (ii) If $det(\mathbf{A}) > 0$, then $L_{\mathbf{A}}$ preserves orientation.
- (iii) If $det(\mathbf{A}) < 0$, then $L_{\mathbf{A}}$ reverses orientation.
- (iv) If $det(\mathbf{A}) = 0$, then $L_{\mathbf{A}}$ maps \mathbb{R}^3 to a lower-dimensional subspace.

Here the transformation could be implemented as a continuous deformation and/or rotation of solid objects if, and only if, it preserves orientation.

The matrix $\mathbf{A} = \begin{bmatrix} 1 & 2 \\ 3 & 5 \end{bmatrix}$ defines a linear transformation $L_{\mathbf{A}}$ that maps the rectangle R with vertices [0,0],[0,3],[4,0],[4,3] onto a quadrilateral Q.

Question 64.1: Find the area of Q.

Question 64.2: Does the transformation $L_{\mathbf{A}}$ preserve or reverse orientation?

The matrix $\mathbf{B} = \begin{bmatrix} 3 & 4 \\ 5 & 6 \end{bmatrix}$ defines a linear transformation $L_{\mathbf{B}}$ that maps the disc D whose center is the origin and whose radius is r = 2 onto a region E whose boundary is an ellipse.

Question 64.3: Find the area of the region E.

Question 63.4: Does the map $L_{\mathbf{B}}$ preserve or reverse orientation?

Question 64.5: Consider the diagonal matrix $\mathbf{D} = \begin{bmatrix} 2 & 0 & 0 \\ 0 & -0.1 & 0 \\ 0 & 0 & -3 \end{bmatrix}$

How does $L_{\mathbf{D}}$ change volumes, if at all? Does $L_{\mathbf{D}}$ preserve orientation? Does $L_{\mathbf{D}}$ change orientation?

Question 64.6: Consider the matrix **B** of Question 62.3 of Module 62. How does $L_{\mathbf{B}}$ change volumes, if at all? Does $L_{\mathbf{B}}$ preserve orientation? Does $L_{\mathbf{B}}$ change orientation?

Question 64.7: Consider the matrix \mathbf{C} of Question 62.4 of Module 62. How does $L_{\mathbf{C}}$ change volumes, if at all? Does $L_{\mathbf{C}}$ preserve orientation? Does $L_{\mathbf{C}}$ change orientation?