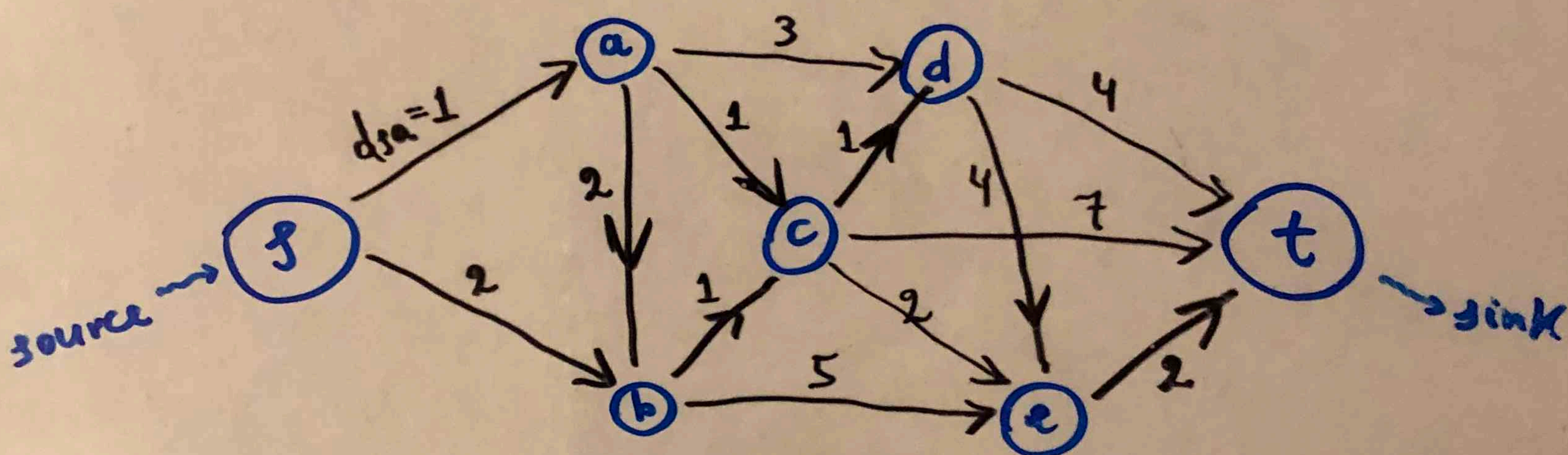


Special cases of Min-Cost Flow Problem (cont.)

Shortest Path Problem

- one source & one sink
- distances on arcs
- Find the shortest path from source to sink



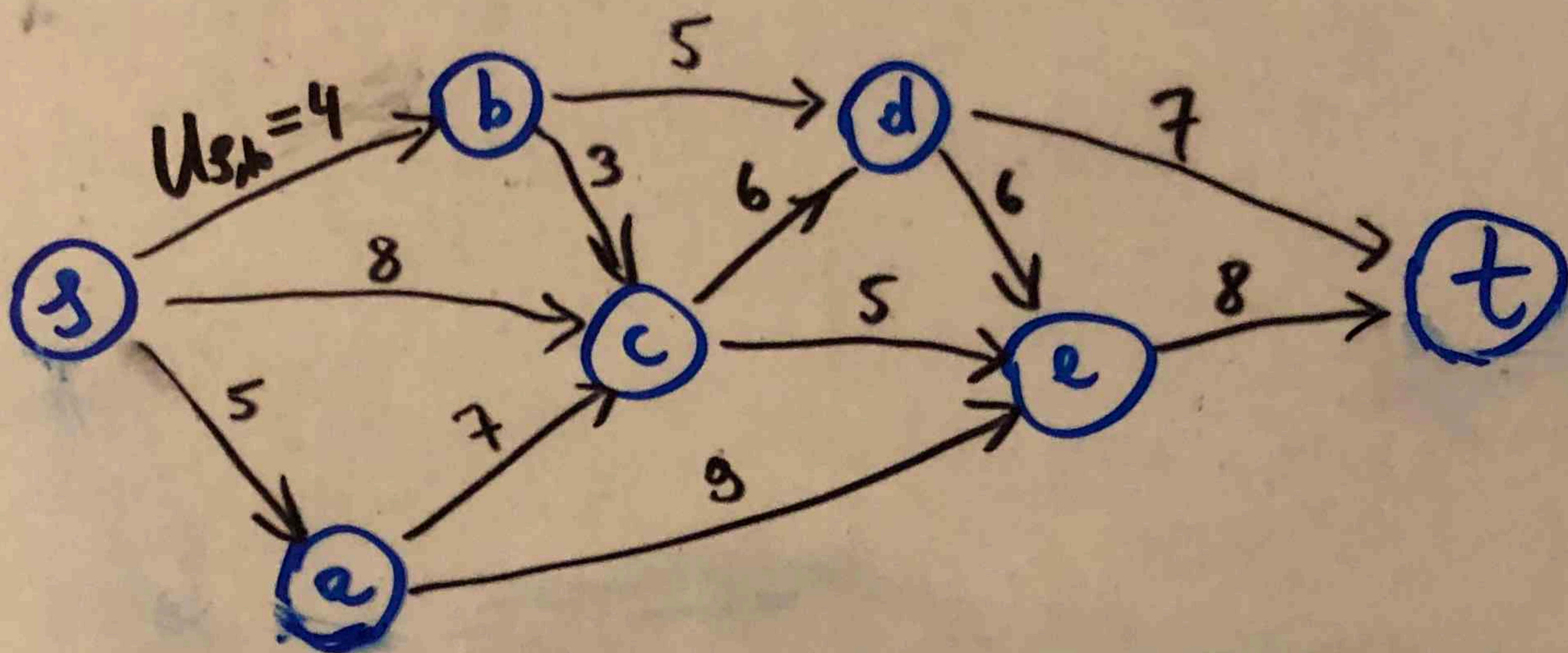
Q: How to formulate this as a min-cost flow problem.

- ▶ Assign $b_s = 1$, $b_t = -1$, $b_i = 0$ for all other nodes i
- ▶ costs = distances
- ▶ no upper bounds necessary

Note: • This formulation gives a reasonable solution to Shortest Path problem based on Integrality Property.

Maximum Flow Problem

- source s and sink t
- upper bound U_{ij} on each arc $i \rightarrow j$
- Goal: Send as much flow as possible from s to t .



▼ Formulating a Min-Cost Flow Problem

- Set $C_{ij} = 0$ for all existing arcs $i \rightarrow j$
- Set $b_s = F$, $b_t = -F$ where F is a safe upper bound for max flow
- $b_i = 0$ for other nodes

- Add an arc $s \rightarrow t$ with $C_{s,t} = M$, $U_{s,t} = +\infty$ ($M \gg 0$ is a large #)
- Since $C_{s,t} = M$, the Min-cost Flow Problem will send as much as possible by real arcs and the rest of the demand by artificial arc $s \rightarrow t$.

Note: Integrality property will provide a reasonable (integer) sol-n to the problem

(3)

All the special cases we discussed,

Transportation Problem

Assignment Problem

Shortest Path Problem

Max Flow Problem

can be solved in two ways:

1) formulating as Min-Cost Flow and applying a Min-Cost Flow algorithm (e.g., Network Simplex)

2) Applying special-purpose algorithms designed for each of those cases

An example of a Network Model which is not a special case of Min-Cost Flow:

Min Spanning Tree Problem

Given • undirected graph $G = (V, E)$, $|V| = n$

• cost function! $c: E \rightarrow \mathbb{R}$

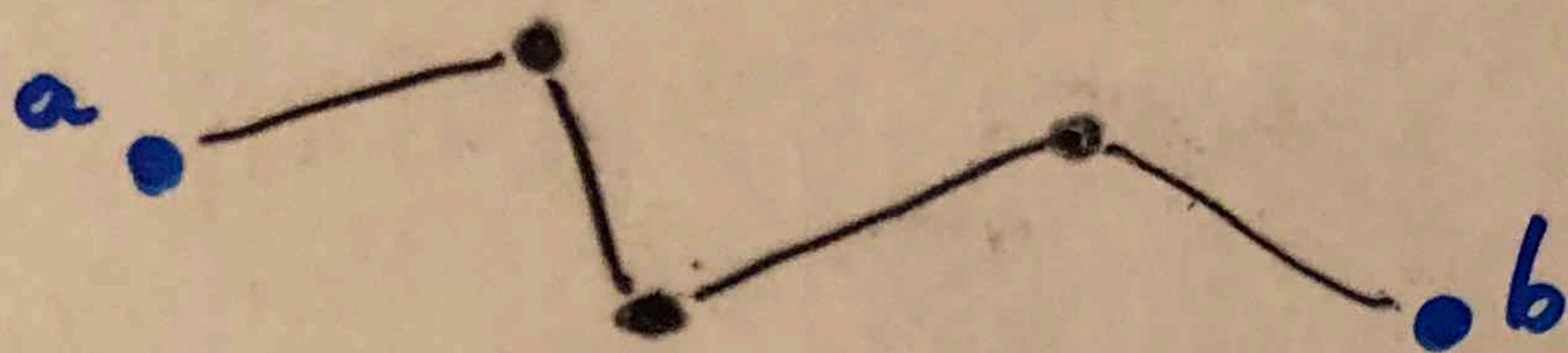
Find min-cost spanning tree for V .

That is, find subset of arcs $E' \subseteq E$ which connects any two nodes of V with minimal possible cost.

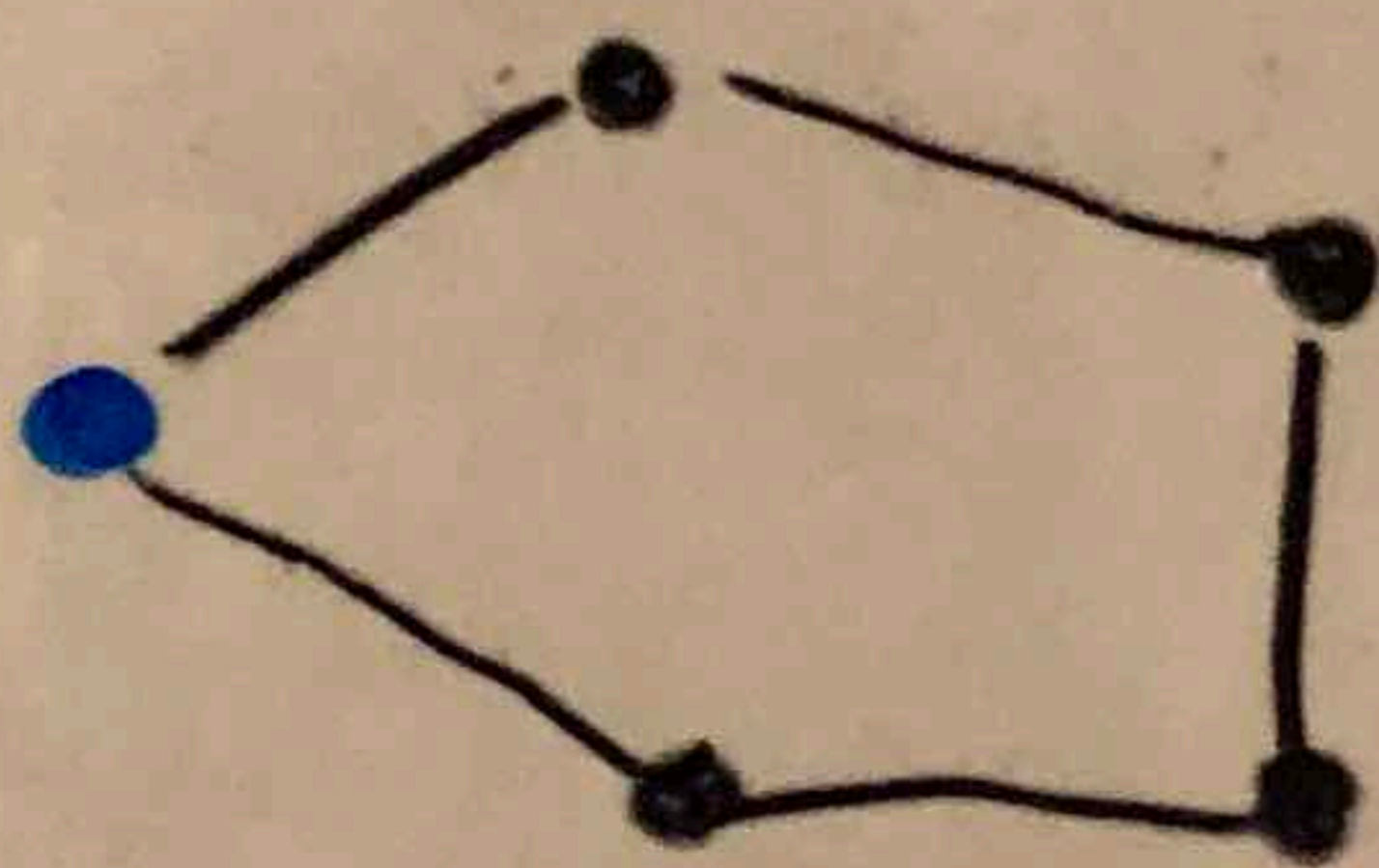
Some Terminology of Networks

(before going to Min Span.. Tree problem)

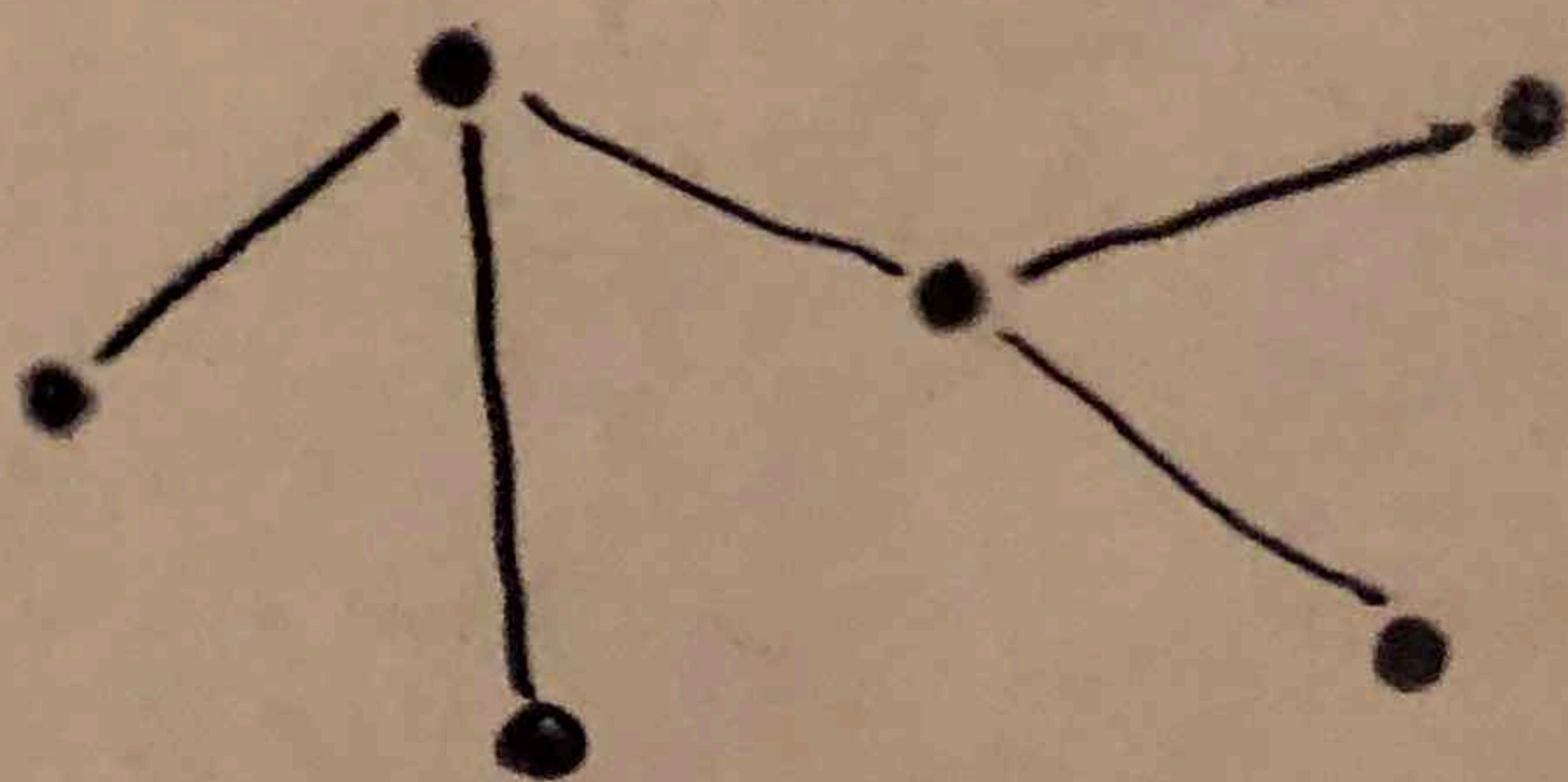
- A path between two nodes is a sequence of distinct arcs connecting these nodes.



- A path that begins and ends at the same node is called a cycle.

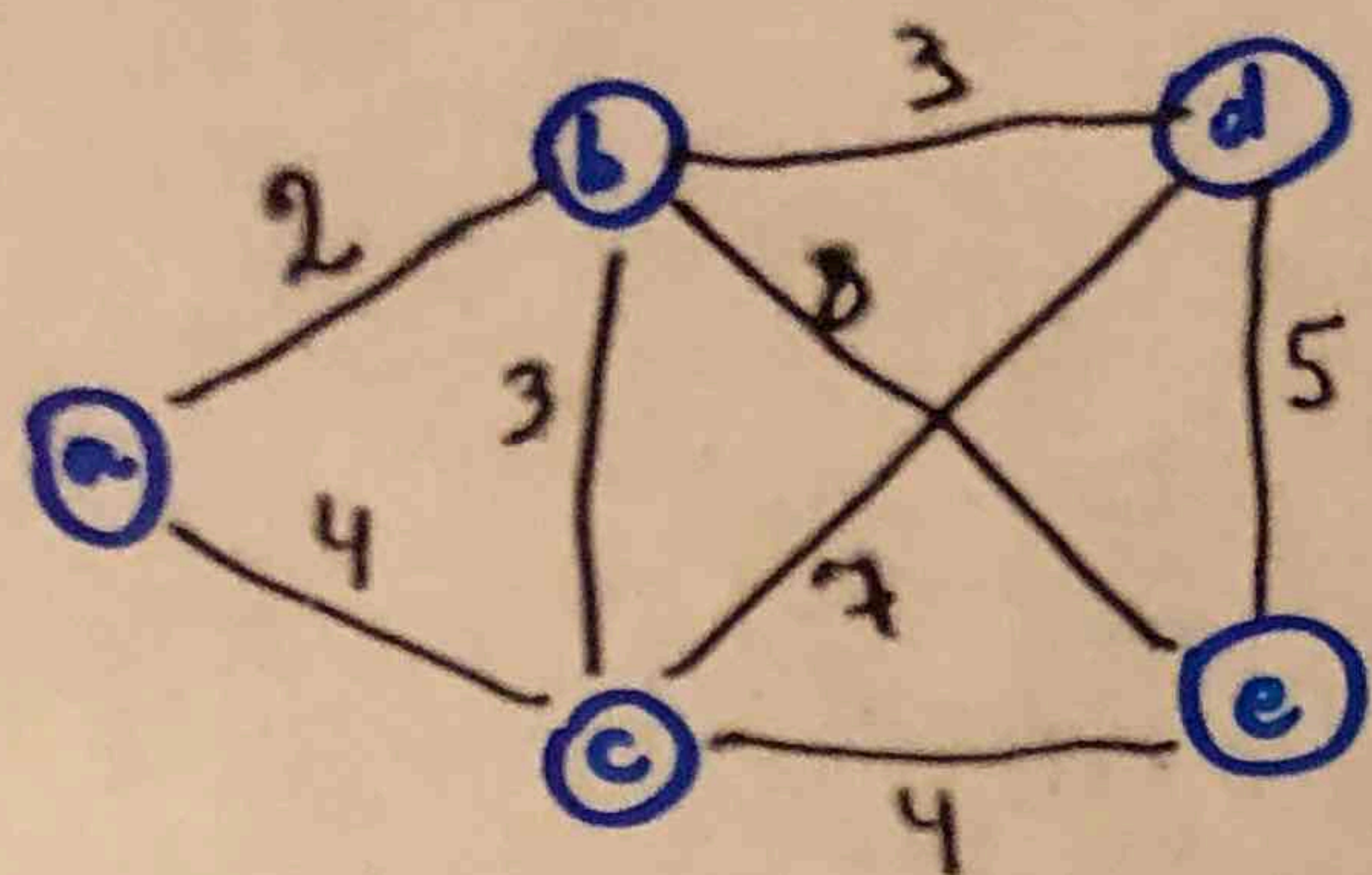


- Two nodes are connected if there is a path between them.
- A graph is connected if every pair of nodes is connected.
- A graph is acyclic if it doesn't have any cycle.
- A graph is called tree if it is connected and acyclic.

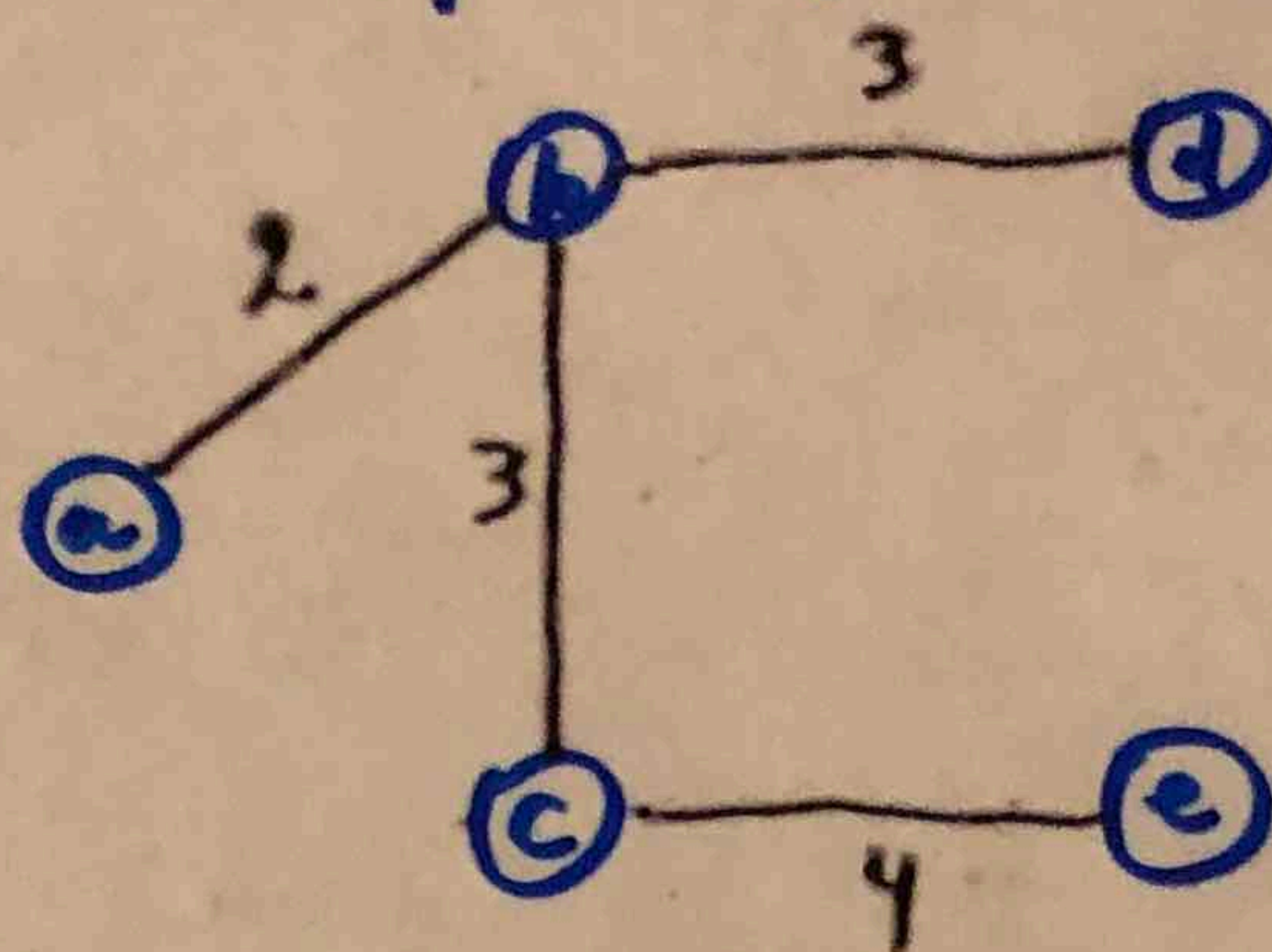


Example:

$G=(V,E)$



min-spanning tree: $G=(V,E)$



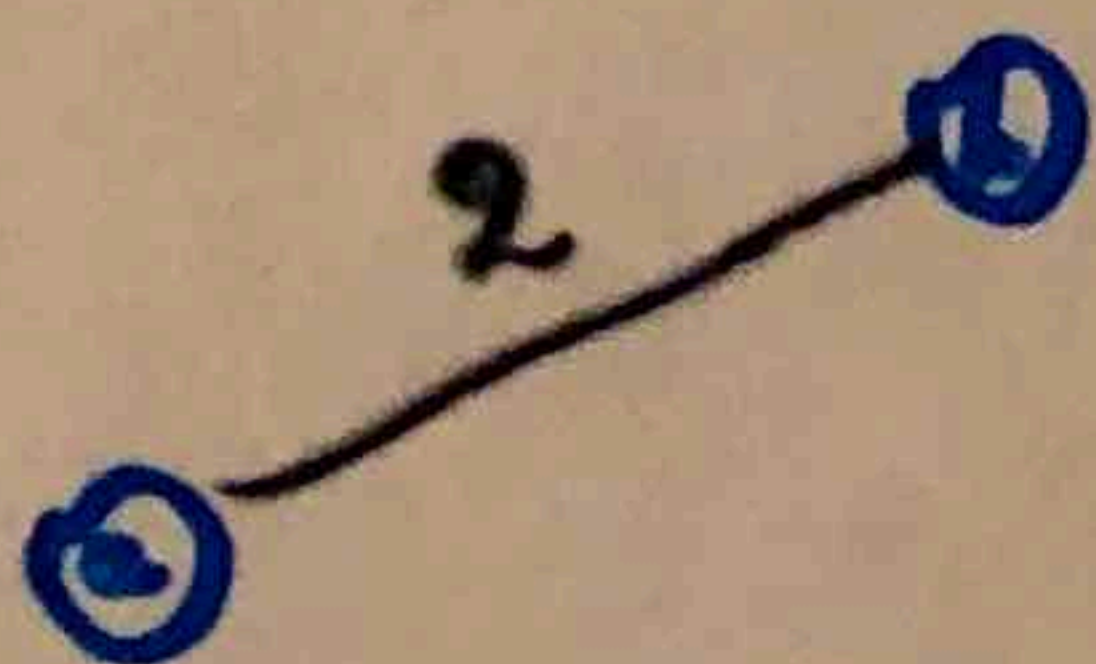
Algorithm for solving Min Span. Tree Problem

- Select any node arbitrarily, connect to its nearest node.
- REPEAT
Identify the unconnected node which is closest to a connected node; connect those 2 nodes.
until all nodes are connected.

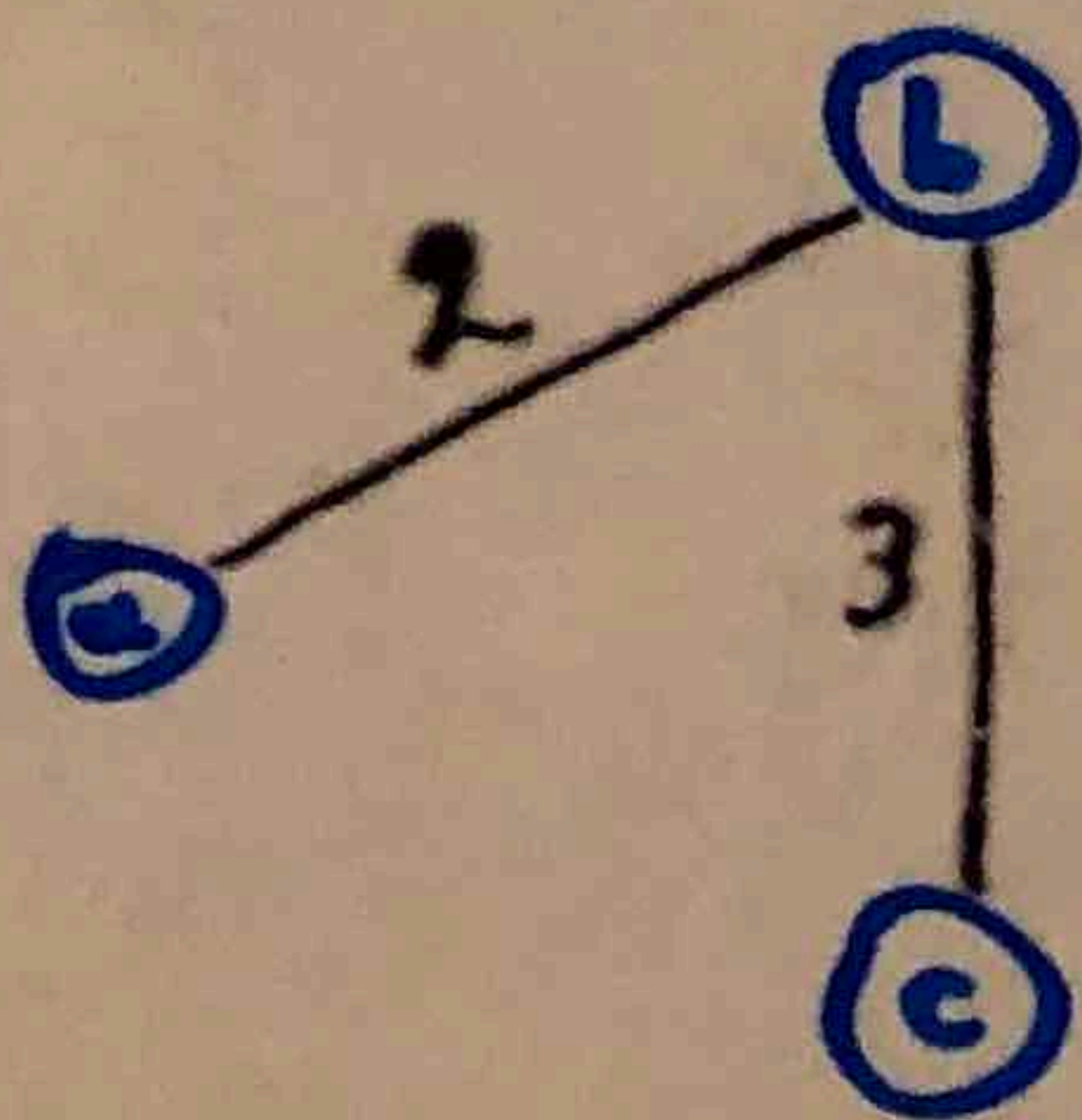
Ex. (cont.)

- Start with node a

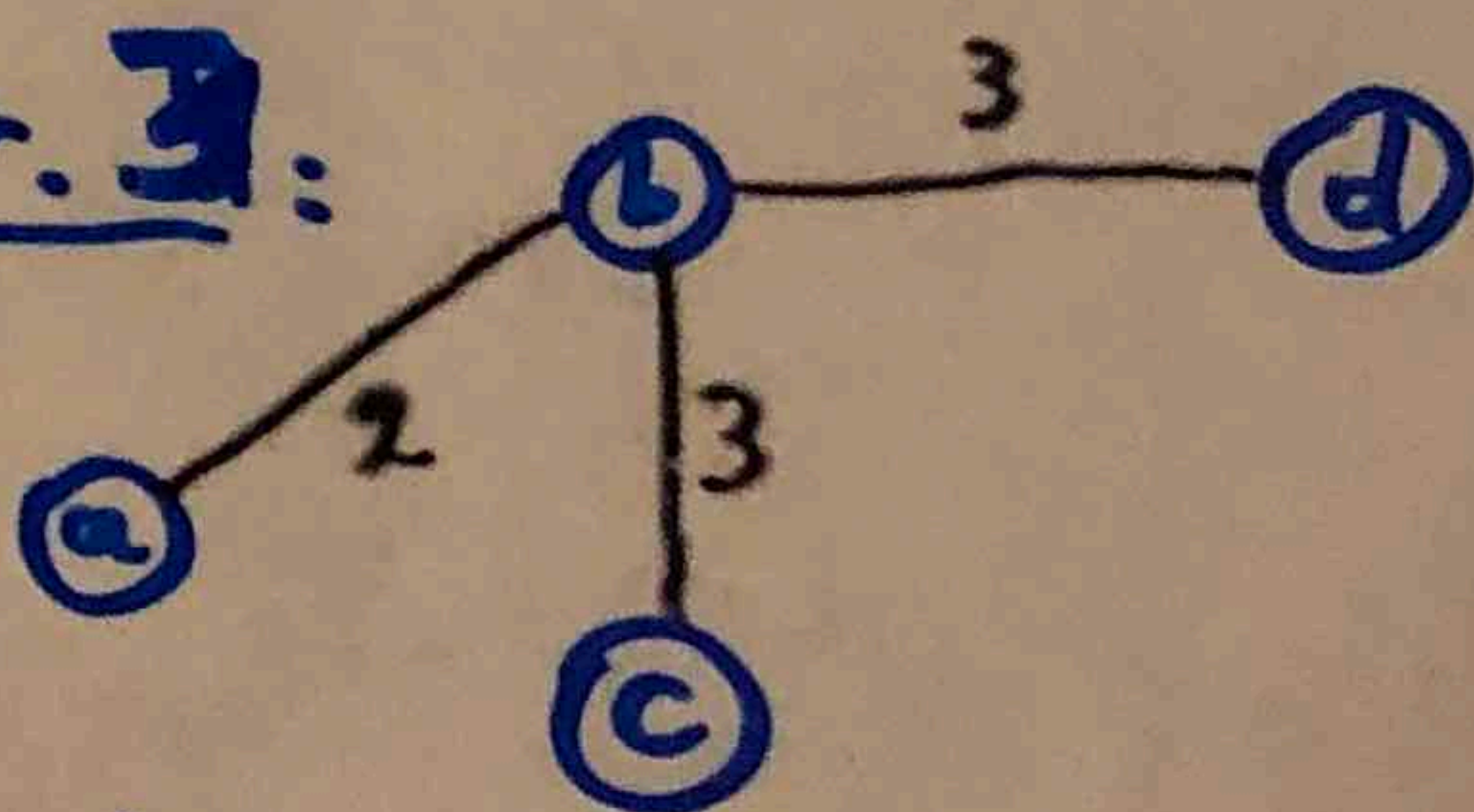
• Iter. 1:



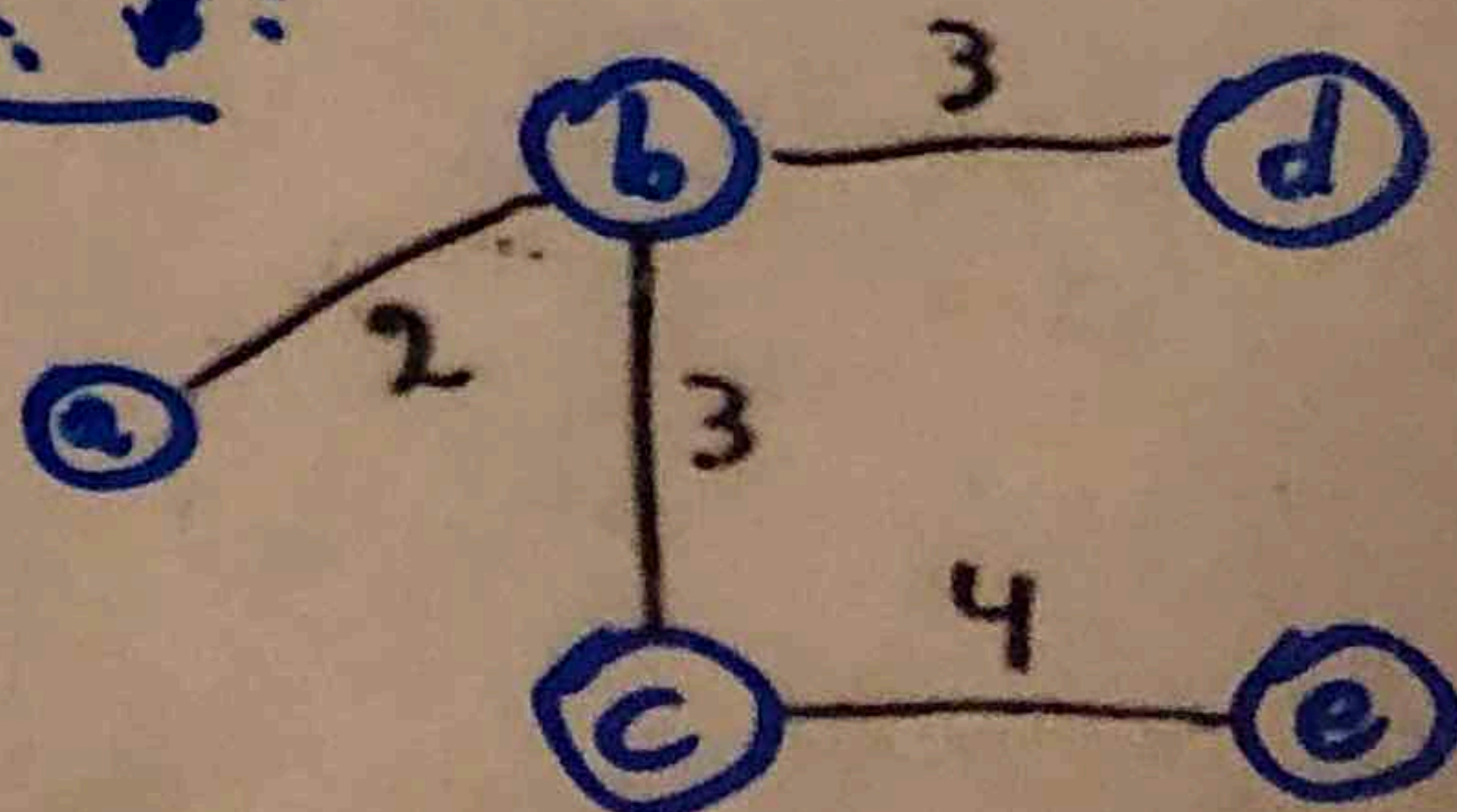
• Iter. 2:



• Iter. 3:



• Iter. 4:



Note: If $|V|=n$ then spanning tree of V has $n-1$ arcs. (5)

Now back to

Min Cost Flow Problem

Recall LP formulation:

$$\min \sum_{i \rightarrow j \in E} C_{ij} X_{ij}$$

$$\text{s.t.} \quad \sum_{k: (j,k) \in E} X_{j,k} - \sum_{i: (i,j) \in E} X_{ij} = b_j, \quad \forall \text{node } j$$

(cons.-of-flow)

$X_{ij} \geq 0, \quad \forall \text{arc } i \rightarrow j$
(we will use this simplified version of bound constraints)

- Want to give a streamlined version of Simplex for solving this specific LP.

It is called Network Simplex.

- Correspondence between basic solutions and spanning trees

▼ # of constraints = n but one of the constraints is redundant \Rightarrow

of nonredundant constraints is $n-1$

⇒ # of basic variables is $n-1$

⇒ in any basic sol-n, only $n-1$ arcs have nonzero values

▼ basic arcs never form (undirected) cycles.

▼ $n-1$ basic arcs; } ⇒ basic arcs form a spanning tree for V
no cycles

▼ Thus, for Min Cost Flow Problem

basic solutions ⇔ spanning tree solutions

Example:

